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A METLAB tutorial on using the package for Robotics is included as an appendix. A full chapter on the industrial applications of robots. All important industrial robot configurations with varying degrees of freedom are covered in various chapters and solved examples. An elaborate chapter (Chapter 9) devoted to Robotic Sensors and Vision.

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This book introduces the science and engineering of mechanical manipulation. This subdiscipline of robotics has its foundations in several classical fields. The major relevant fields are mechanics, control theory, and computer science. In this book, Chapters 1 through 8 cover topics from mechanical engineering and mathematics,

Introduction to Robotics - Mechanical Engineering

R K Mittal is an Educator, Author and has been the Director of BITS Pilani. He has co-authored two books, the first being Robotics And Control and the second, Elements of Manufacturing Processes. He completed his B.E. and M.E. in Mechanical Engineering from BITS where he also pursued his Ph.D. in Software engineering in 1992.

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